

## Lecture 8: Ray tracing

- (1) Note that from Equation

$$\text{dir}_{rc} = -Nn + W\left(\frac{2c}{nCols} - 1\right)u + H\left(\frac{2r}{nRows} - 1\right)v$$

that along a scan line, the direction of one ray can be found incrementally from that of the previous one by means of a single vector addition: Express  $\text{dir}_{r,c+1}$  by  $\text{dir}_{r,c}$ .

- (2) When and where does the ray  $(20-t, 8-2t, 3+t)$  hit the plane created in SDL by: translate 4 5 6 rotate 90 1 0 0 plane?
- (3) Write the routine `xfrmRay()` that `hit()` uses to transform a ray into the generic coordinates of a sphere. Give careful attention to the difference between transforming a point and a vector.
- (4) Implementation of `hit()` for the tapered cylinder.
- (5) Implementing the generic box extent test. Adjust the `Cube :: hit()` method to develop the routine `bool rayHitsBoxExtent(ray& ray, Cuboid& cub)` that tests whether the given ray intersects the extent described in `cub`. This entails simplifying `hit()` without altering its logic. Show how the numer and denom values needed for each plane of the box depend on the data in `cub`. As each plane of the box is intersected by the ray, the candidate interval  $(t_{in}, t_{out})$  is updated, and if the interval vanishes, an early out occurs and the test returns true.